

6.2 GLM

Def. 6.51 Za denu eksp. funkciju $\{P_{\mu, \phi} : \mu \in \mathcal{M}, \phi \in \Phi\}$, GLM pretpostaveja da su Y_1, \dots, Y_n nezavisne t.d.

$$Y_i \sim P_{\mu_i, \phi_i}, i=1, \dots, n$$

mi denu

• $g(\mu_i) = (x^{(i)})^T \beta$ za neki $\beta \in \mathbb{R}^p, i$ tzv. $\mu_i = g^{-1}(n_i)$

kanoniku veze

$g: \mathcal{M} \rightarrow \mathbb{R}$ (pazovate!), te \leftarrow npr. $u \in \mathbb{R}^{(m,p)}$ takoz, $\phi=1$ te $w_i = m_i$

• $\phi_i = \frac{\phi}{w_i}$, uz "tezine" $w_1, \dots, w_m > 0$ (pazovate), $i \phi > 0$ potencijalno nepoznat [ϕ tekster zrenu parameter disperzije, kao $i \phi_i$].

Nop.1 Pretpostavljamo da je $p \leq n$, rang(X) = p, g strogo monotona, te da $\exists g''$.

Često za g uzimamo tzv. kanonsku tj. veze del. sa

$$g_c(\mu) := \theta(\mu) \rightarrow \text{tada } \boxed{\theta_i = \theta(\mu_i) = \theta(g_c^{-1}(n_i)) = n_i}$$

[g_c ima neka dobra svojstva, ali nije apriori jasno da je to uvek najbolji izbor za g !]

- $\{N(\mu, \sigma^2)\}$ $\rightarrow g_c(\mu) = \mu$, tj. $\mu_i = n_i$
- $\{\text{Pois}(\lambda)\}$ $\rightarrow g_c(\mu) = \log \mu$, tj. $\mu_i = e^{n_i}$

• $\left\{ \frac{1}{m} B(m, p) \right\} \rightarrow g_z(\mu) = \text{logit}(\mu) = \log\left(\frac{\mu}{1-\mu}\right)$, [66]

fj. $\mu_i = \text{expit}(m_i) = \frac{e^{m_i}}{1+e^{m_i}}$

"logistički model"
 ($m=1 \Rightarrow$ "logist. regresija")
 ($m \in \{0, 1, 3\}$)

6.2.1 Procjenitelji za β i ϕ

$\hat{\beta} := \hat{\beta}_{MLE}$,

gdje $(\hat{\beta}_{MLE}, \hat{\phi}_{MLE})$ maksimizira

$Q(\beta, \phi) := \log \prod_{i=1}^n f_{\mu_i, \phi_i}(y_i)$

$= \sum_{i=1}^n \frac{w_i}{\phi} \left\{ \theta(\mu_i) \cdot y_i - b(\theta(\mu_i)) \right\}$
 $\theta = g^{-1}(x^{(i)T} \beta)$

(6.4)

$+ \sum_{i=1}^n \log h(y_i, \phi/w_i)$

$\hat{\beta}_{MLE}$ neovisan od $\hat{\phi}_{MLE}$.

[Interpretacija $\hat{\beta}$ -a?]

$\hat{\mu}(x) = \hat{E}[Y | X=x] := g^{-1}(x^T \hat{\beta})$, $x \in \mathbb{R}^p$

Ako je $g = g_z \Rightarrow \theta(x_i) = m_i = (x^{(i)T} \hat{\beta})$, pa (DZ) $\hat{\beta}$
 zadovoljava

$\sum_{i=1}^n w_i x_{ij} (y_i - \hat{\mu}_i) = 0$, $\forall j = 1, \dots, p$, (6.5)

tj. ako $\omega_i = 1, \forall i = 1, \dots, n$,

"normalne j(ke"

$$X^T(y - \hat{\mu}) = 0 \quad (6.6)$$

u NLM $\hat{\mu} = X \hat{\beta} \Rightarrow (6.6)$ postaje

$$X^T y = X^T X \hat{\beta}; \hat{\beta} = (X^T X)^{-1} X^T y = \hat{\beta}_{OLS}$$

Ipak, osim u NLM, $\hat{\beta}$ aproksimiramo numeričkim (iterativnim) algoritmima (čak i za $g = gc$).

[Newton-Raphson ili IRLS algoritmom]

Ako je ϕ poznat (npr. $\phi = 1$ u $\{B(m, p)\}$

i $\{Pois(\lambda)\}$ slučajno), $\hat{\phi} := \phi$, a u nepoznatom

$$\hat{\phi} := \frac{1}{n - p} \sum_{i=1}^n \omega_i \frac{(y_i - \hat{\mu}_i)^2}{V(\hat{\mu}_i)} \quad (6.7)$$

Zbog procjene $\hat{\beta}_1, \dots, \hat{\beta}_p$ [generalizirana Pearsonova statistika]

$$\text{motivirano } \Rightarrow \text{Var}(y_i) = \frac{\phi}{\omega_i} V(\mu_i), \forall i = 1, \dots, n. \\ = E[(y_i - \mu_i)^2]$$

Nap. 1 $\hat{\phi} \neq \hat{\phi}_{MLE}$ kada $(n \rightarrow \infty)$

Nap. 2 Pod nekim uvjetima, [generalna teorija MLE]

• $\hat{\phi} \xrightarrow{d.s.} \phi$, te

• $\hat{\beta}$ asimptotski normalna

intervali procjenosti za β_j

6.2.2 Denženca i usporedba modela

Ako imamo model ω_0 koji koristi samo X_{11}, \dots, X_{p_0} , i ω_1 koji koristi X_{11}, \dots, X_{p_1} ($p_0 < p_1 \leq p$), želimo testirati

$$H_0: \beta_{p_0+1} = \dots = \beta_{p_1} = 0$$
$$H_1: \exists i \in \{p_0+1, \dots, p_1\} \text{ t.d. } \beta_i \neq 0.$$

Ako je H_0 točan, kada $n \rightarrow +\infty$,

$$T := 2 \left(\underset{\substack{\uparrow \\ \omega_1}}{\ell(\hat{\beta}_1, \phi)} - \underset{\substack{\uparrow \\ \omega_0}}{\ell(\hat{\beta}_0, \phi)} \right) \sim \chi^2_{p_1 - p_0} \quad (6.8)$$

odbacujemo H_0 ako $T > (1-\alpha)$ -kvantila $\chi^2_{p_1 - p_0}$ raspodjele.

Ipak, T moguće izračunati samo ako je ϕ potpuno.

Općenito, za svaki (sub)model ω p komponenti definiramo

denženca modela D

$$D(\hat{\beta}) := 2 \left(\ell(\hat{\beta}_{\text{sat}}, \phi) - \ell(\hat{\beta}, \phi) \right) \quad (6.9)$$

gdje se $\ell(\hat{\beta}_{\text{sat}}, \phi)$ dobije tako da u (6.4)

stavimo $\hat{\mu}_i := y_i, \forall i=1, \dots, n$ ("saturirani model")

Iz (6.4) slijedi da D ne visi o ϕ !

Pod nekim uvjetima, kada $n \rightarrow \infty$,

$$T' := \frac{1}{\hat{\phi}} \left(D(\hat{\beta}_0) - D(\hat{\beta}_1) \right) \sim \chi^2_{p_1 - p_0} \quad (6.10)$$

Uopće! Ako $\hat{\phi} = \phi$, $T' = T$

6.2.3 Odlučiv modela i generalizacije Glava

↳ pretp. da je ϕ poznat.
• Za odlučiv modela (tj. kovarijatu), možemo koristiti CV

ili AIC/BIC kriterije gdje je

$$AIC(\hat{\beta}) = -l(\hat{\beta}, \phi) + 2 \cdot (P)$$

↑ broj konstantih kovarijeta

$$BIC(\hat{\beta}) = -l(\hat{\beta}, \phi) + \log(n) \cdot P.$$

• Ridge ili lasso regulacija:

$$\hat{\beta}^{ridge} := \underset{\beta \in \mathbb{R}^P}{\text{argmin}} -l(\beta, \phi) + \lambda \cdot \|\beta\|_2^2$$

$$\hat{\beta}^{lasso} := \underset{\beta \in \mathbb{R}^P}{\text{argmin}} -l(\beta, \phi) + \lambda \cdot \|\beta\|_1$$

• Generalizirani aditivni model (GLM):

$$g(\mu_i) = \sum_{j=1}^P \tau_j(x_{ij}), \quad i=1, \dots, n$$

↑ procjenjuje se neparametarski