

Abstract

The development of a unified similarity scaling has so far failed over complex surfaces, as scaling studies show large deviations from the empirical formulations developed over flat and horizontally homogeneous terrain and also large deviations between the different complex terrain datasets. However, a recent study of turbulence anisotropy for flat and horizontally homogeneous terrain has shown that separating the data according to the limiting states of anisotropy (isotropic, two-component axisymmetric and one component turbulence) improves near-surface scaling. In this paper we explore whether this finding can be extended to turbulence over inclined and horizontally heterogeneous surfaces by examining near-surface scaling for twelve different datasets obtained over terrain ranging from flat to mountainous. Although these datasets show large deviations in scaling when all anisotropy types are examined together, the separation according to the limiting states of anisotropy significantly improves the collapse of data onto common scaling relations indicating the possibility of a unified framework for turbulence scaling. The causes for the breakdown of scaling and the physical mechanisms behind the turbulence complexity encountered over complex terrain are identified and shown to be related to the distance to the isotropic state, prevalence of directional shear with height in mountainous terrain and the existence of non-isotropy in the inertial subrange. A measure of turbulence complexity is finally developed.

1 Introduction

Atmospheric surface-layer (ASL) similarity theory was developed as a unified theory of statistically stationary turbulence over horizontally homogeneous and flat terrain [HHF; e.g. *Monin and Yaglom*, 1971]. Although never meant to be employed over heterogeneous and non-flat surfaces, the lack of a better framework has thus far led to similarity theory being employed in weather prediction and climate models over all types of terrain [cf. *Rotach et al.*, 2017]. Given the prevalence of heterogeneity of the earth land surface [e.g. *Rotach et al.*, 2014], adaptations were developed by reconciling theory and application under the principle of ‘*local*’ homogeneity in order to be able to model real flows over heterogeneous surfaces. Meaning, that over small enough regions, sampled long enough, what a-priori might resemble a heterogeneous surface, can ultimately be interpreted as homogeneous. While these practical adjustments work well for regions with weak heterogeneities [e.g. *Sfyri et al.*, 2018], similarity relationships become severely challenged in complex terrain [e.g. *Martins et al.*, 2009; *Nadeau et al.*, 2013; *Sfyri et al.*, 2018] where terrain slope, land-use characteristics and complexity of the flow itself (e.g. low-level jets, flow separation etc.) cause turbulence to exhibit increasing complex structure [e.g. *Nadeau et al.*, 2013; *Oldroyd et al.*, 2016; *Stiperski and Rotach*, 2016; *Grachev et al.*, 2016]). In this work, reference to complex terrain is understood as topographic perturbations that induce spatial and/or temporal perturbations to the atmospheric flow with a timescale shorter than that of the diurnal cycle or mesoscale phenomena (e.g., sloped terrain, ground roughness and thermal patchiness, obstacles, etc.)

Numerous studies have illustrated the adequacy of similarity theory under idealized terrain and flow conditions [e.g. *Panofsky and Dutton*, 1984; *Wyngaard*, 2010]. Nonetheless, an important degree of scatter still exists, particularly for horizontal velocity variances that are commonly assumed not to obey surface layer scaling [e.g. *Kaimal and Finnigan*, 1994; *Wyngaard*, 2010; *Banerjee et al.*, 2015; *Chamecki et al.*, 2017]. This scatter also persists despite the advanced post-processing techniques and progressively more restrictive quality criteria imposed on the data. In an effort to overcome these challenges, *Stiperski and Calaf* [2018] employed a novel approach by examining traditional similarity scaling relations over flat and horizontally homogeneous terrain based on clustering the data according to anisotropy. Results of this work illustrated a strong dependence between the quality of the scaling fit and the characteristic topology of the turbulent flow, showing that the similarity scaling significantly improves when the turbulent flow is a-

62 priory classified according to the anisotropy type. In essence, results illustrated that isotropic
 63 and two-component axisymmetric type turbulence scales the best (*i.e.*, show closest col-
 64 lapse on a scaling line), although for horizontal velocity components, the two types of
 65 anisotropy were shown to follow different scaling curves. This finding could explain the
 66 commonly encountered large scatter observed for scaled standard deviations of horizon-
 67 tal velocities. On the other hand, one-component turbulence strongly departs from regu-
 68 lar scaling curves. These results together with the possibility of predicting the anisotropy
 69 type based on larger scale variables as shown in *Stiperski and Calaf* [2018], promised to
 70 be a powerful tool in improving similarity scaling relations.

71 In complex terrain, on the other hand, despite the progressively more severe restric-
 72 tions imposed on the experimental data [cf. *Stiperski and Rotach*, 2016], significant scat-
 73 ter and a relevant degree of discrepancy between the experimental data and similarity
 74 relationships are more evident. Even more, all the studies examining the applicability
 75 of surface-layer scaling for data obtained over diverse complex settings [*e.g.*, *Park and*
 76 *Park*, 2006; *de Franceschi et al.*, 2009; *Martins et al.*, 2009; *Nadeau et al.*, 2013; *Kral et al.*,
 77 2014; *Babić et al.*, 2016a,b; *Grachev et al.*, 2016; *Sfyri et al.*, 2018] show that the scal-
 78 ing relations not only differ from the functional relations obtained over flat and horizon-
 79 tally homogeneous terrain, but also differ from site to site, suggesting that scaling might
 80 be inherently ‘*local*’ (*i.e.*, *location dependent*) and therefore no unified theory of turbu-
 81 lence over all types of surfaces is possible. The search for an additional scaling variable
 82 in complex terrain that could explain these discrepancies has so far been proven unsuc-
 83 cessful, as the only systematic study to date [*Sfyri et al.*, 2018] found no clear relation-
 84 ship between scaling and slope angle, at least for the scaled standard deviations of scalars.
 85 Still, the data from progressively more complex surfaces do show larger deviations from
 86 the scaling curve and generally larger scatter, even if the exact mechanism behind this
 87 finding escapes clear explanation.

88 In this work, and based on the earlier approach first introduced in *Stiperski and*
 89 *Calaf* [2018], we present a new interpretation of the a-priori mismatch of near-surface
 90 data in complex terrain and traditional scaling relations based on the anisotropy of the
 91 turbulence stress tensor. The results show that similar to flat and horizontally homo-
 92 geneous terrain, separating the complex terrain data according to anisotropy significantly
 93 improves scaling, offering a pathway towards a unified theory of turbulence. In addition,
 94 we provide a novel approach that defines *complexity* as not only exclusively associated
 95 with terrain characteristics, but also to the actual resultant turbulence structure. The
 96 physical mechanisms causing this complexity are then identified. This new definition of
 97 complexity could facilitate comparison between different datasets collected in regions with
 98 different atmospheric and topographic characteristics.

99 The paper is organized as follows: in Section 2 the datasets and post-processing
 100 methods are presented, the anisotropy analysis is reviewed, and scaling relations intro-
 101 duced; Section 3 presents the relationship between similarity scaling and the anisotropy
 102 of turbulence over complex terrain; Section 4 identifies a measure of turbulence complex-
 103 ity and examines its relation to the physical mechanisms acting in complex terrain; an
 104 extended discussion of the results and implications for similarity theory as well as con-
 105 clusions are provided in Section 5.

106 2 Methodology

107 2.1 Datasets

108 In this study we examine turbulence measurements from twelve flux towers located
 109 on surfaces of different complexity, ranging from flat to highly complex mountainous ter-
 110 rain. These are part of well known datasets and include the tower at Cabauw experi-
 111 mental site for atmospheric research (Cesar) of the Royal Netherlands Meteorological Insti-

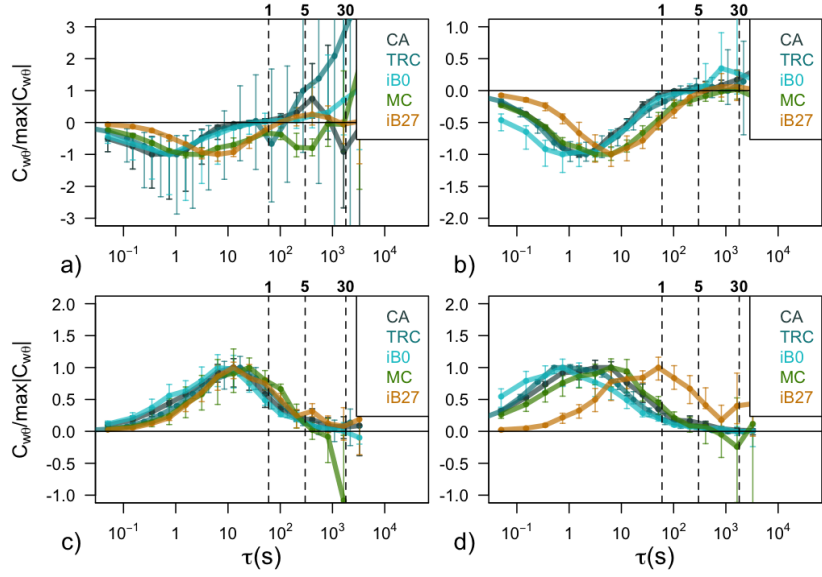
112 tute [e.g., *Beljaars and Bosveld, 1997*], the Cooperative Atmosphere – Surface Exchange
 113 Study 1999 [CASES-99; *Poulos et al., 2002*], the Terrain-induced Rotor Experiment [T-
 114 Rex; *Grubišič et al., 2008*], the Mountain Terrain Atmospheric Modeling and Observa-
 115 tions [MATERHORN; *Fernando et al., 2015*], the Second Meteor Crater Experiment [METCRAX
 116 II; *Lehner et al., 2016*], and the Innsbruck Box [i-Box; *Rotach et al., 2017*]. A detailed
 117 description of the datasets is given in Table 1. The dataset that conforms to the flat and
 118 horizontally homogeneous terrain the best is CASES-99. Already studied in *Stiperski and*
 119 *Calaf [2018]* it forms the basis of the current analysis. The data consist of a month of
 120 measurements from a 60 m tower with 7 levels of sonic anemometers. Due to issues with
 121 the anisotropy of the CSAT3 measurements during stable periods identified in *Stiper-*
 122 *ski and Calaf [2018]*, here we only study the levels with ATI-K probes in stable condi-
 123 tions. Cabauw data can also be considered flat, however, horizontally weakly inhomog-
 124 eneous [*Sfyri et al., 2018*]. The other datasets were chosen according to their increas-
 125 ing terrain complexity. The Central tower from T-Rex is located at an almost flat val-
 126 ley floor, however, its setting within a mountain valley (*i.e.*, complex terrain) neverthe-
 127 less has a profound influence on scaling [*cf. Babić et al., 2016b*]. The i-Box0 valley floor
 128 site (see Table 1), apart from being located in a narrower valley than T-Rex, is addition-
 129 ally characterized by larger surface heterogeneity, given that it is surrounded by mixed
 130 agricultural land. The rest of the datasets are located on slopes of various steepness and
 131 are strongly influenced by flows associated with sloped terrain (*e.g.*, thermally-driven
 132 katabatic and anabatic flows and dynamically-driven wind systems) and/or heterogene-
 133 ity. The i-Box1 station has a small slope angle, however, the influence of surface hetero-
 134 geneity (corn and meadows) for this station is larger than the influence of sloping ter-
 135 rain because the dominant wind direction is across the slope. The same is true for T-
 136 Rex West tower, although there the wind rose also shows a large influence of katabatic
 137 flows as well as downslope windstorms [*Babić et al., 2016b*]. On the other hand, deep
 138 katabatic flows with jet maxima between 20 and 40 m above ground level (agl) develop
 139 regularly at the METCRAX II NEAR tower [*cf. Savage et al., 2008; Lehner et al., 2016*].
 140 Persistent shallow katabatic flows with a jet maximum at around 5 m agl are also found
 141 at MATERHORN ES4 and ES5 towers located at the top of a relatively shallow slope
 142 below a couloir [*Grachev et al., 2016*]. Even shallower katabatic flows develop at the steeper
 143 i-Box10 and i-Box27 stations. The i-Box mountain top station (i-BoxTop) represents the
 144 most complex site due to its location on a ridge exposed to flow from all sides that, de-
 145 pending on wind direction, responds to very different slope angles. Operating continu-
 146 ous turbulence measurements at this station is challenging therefore only seven months
 147 of measurements were analyzed in this study, as opposed to the other i-Box stations where
 148 one year of data was analyzed. The datasets (in both Table 1 and future Figures) are
 149 a-priori subjectively ordered according to their slope angle, with colder colors represent-
 150 ing gentler slopes (flat terrain being considered more ideal than the flat valley floor lo-
 151 cations) and warmer colors progressively steeper slope angles (4 - 27°).

158 2.2 Data treatment and quality control

159 To remove the inconsistencies in data processing applied by different groups respon-
 160 sible for each of the datasets, we reanalyzed all the data with a processing routine de-
 161 scribed in *Stiperski and Calaf [2018]*. First, the Multi-resolution flux decomposition [MRD,
 162 *e.g., Vickers and Mahrt, 2003*] technique was used to determine the optimal averaging
 163 time for daytime and nighttime turbulence (Figure 1). As in *Stiperski and Calaf [2018]*
 164 we separate the data into strongly and weakly stable/unstable regimes to examine how
 165 the averaging time depends on the stability. The results show that for the examined datasets
 166 a 1 min averaging time for stable stratification and 30 min averaging time for unstable
 167 stratification generally capture the majority of turbulence contributions to the flux while
 168 eliminating most of the (sub)mesoscale effects. The obvious exception here is the i-Box27
 169 steep slope station (orange line in Figure 1). At that station very stable conditions are
 170 rarely encountered, therefore 1 min average slightly underestimates the nighttime fluxes.

Table 1. Information on the datasets used in the study.

Station	Official Name	Short Name	Location	Terrain Complexity	Measurements heights [m]	Slope Angle [°]	Surface Type	Data length
CASES-99	CASES-99	CA	Kansas	flat	5, 10, 20, 30, 40, 50, 55	< 0.5	Grassland	October 1999
Cabauw	Cabauw	CB	Netherlands	flat	3, 60	< 0.5	Grassland	July-October 2007
T-RexC	Central Tower	TRC	California	flat valley floor	5, 10, 15, 20, 25, 30	< 0.5	Desert	March-May 2006
i-Box0	CS-VF0	iB0	Austria	flat valley floor	4, 8.7, 16.9	< 0.5	Mixed Agricultural	January-December 2015
i-Box1	CS-SF1	iB1	Austria	flat foothills	6.6	1	Alpine meadow and agricultural	January-December 2015
METCRAX II	Near Tower	MC	Arizona	Gentle Slope	5, 10, 15, 20, 25, 30, 35, 40, 45, 50	1	Desert	October 2013
T-RexW	West Tower	TRW	California	Gentle Slope	5, 10, 15, 20, 25, 30	3.25	Desert	March-May 2006
MATERHORN ES4	ES4 Tower	MT4	Utah	Gentle Slope	0.47, 2.05, 5.12, 10, 20, 26.5	4	Desert	September-October 2013
MATERHORN ES5	ES5 Tower	MT5	Utah	Gentle Slope	0.55, 2.14, 5.13, 10.13, 20.08	6.4	Desert	September-October 2013
i-Box10	CS-NF10	iB10	Austria	Steep Slope	6.2	10	Alpine meadow	January-December 2015
i-Box27	CS-NF27	iB27	Austria	Steep Slope	6.8	27	Alpine meadow	January-December 2015
i-BoxTop	CS-MT21	iBTop	Austria	Mountain Top	4.67	21	High-Alpine Vegetation	April-October 2015



152 **Figure 1.** Multi-resolution flux decomposition of heat flux for example nights with (a) strongly sta-
 153 ble, (b) weakly stable, (c) strongly unstable and (d) weakly unstable stratification, respectively, for the
 154 lowest measurement level of different datasets (shown in color, see Table 1 for abbreviations). The colored
 155 lines represent medians and are normalized by their maximum value within the turbulence scales for each
 156 dataset so as to eliminate differences in magnitude. Error bars represent the 25 and 75 percentile. Vertical
 157 dashed lines indicate timescales of 1 min, 5 min and 30 min, respectively.

171 The data were then de-trended and block averaged to the given averaging time. Dou-
 172 ble rotation was used to align the coordinates into the streamwise coordinate system.
 173 Zero-plane displacement information was applied to the stations where this information
 174 was available. For i-Box measurements, the zero-plane displacement was calculated based
 175 on the measurements of surrounding vegetation height [Sfyri et al., 2018]. For the two
 176 T-Rex towers the values from the study of Babić et al. [2016b] were used. For the other
 177 datasets the zero-plane displacement was assumed to be zero given the generally low veg-
 178 etation height.

179 Vertical wind shear and temperature gradients needed for calculating the gradient
 180 Richardson number R_i were determined for datasets with multiple measurement levels
 181 (*i.e.*, CASES-99, T-Rex, METCRAX II, MATERHORN and i-Box0). In order to deter-
 182 mine the local wind speed gradient at each measurement height analytic profiles were
 183 fit through the entire tower length. Different analytic formulations were needed for each
 184 dataset due to profiles having different characteristics, particularly in case of the exist-
 185 ence of low-level jets. The formulations used were $x = a + bz + cz^2 + d \log(z)$ for
 186 CASES-99, $x = a + bz + cz^2 + d \log(z) + e \log(z)^2$ for T-Rex, $x = a + bz + cz^2 + dz^3 +$
 187 $e \log(z) + f \log(z)^2$ for METCRAX II, $x = a + b \log(z) + c \log(z)^2$ for MATERHORN,
 188 and finally $x = a + b \log(z) + c \log(z)^2 + d \log(z)^3$ for i-Box0. As a quality check, only
 189 those wind speed gradients in which the root mean square error of the best fit was lower
 190 than 0.3 m s^{-1} were taken into account.

191 All turbulence data were required to pass the basic quality control (test of phys-
 192 ical limits) as well as to satisfy the stationarity test given by Foken and Wichura [1996]
 193 at its standard 30% level. As in Stiperski and Calaf [2018], the stationarity criterion was
 194 dropped for small fluxes *i.e.*, for very unstable conditions stationarity of the momentum
 195 flux was not required, while for near-neutral conditions the same was true for the sta-

196 tionarity of the heat flux. For datasets with multiple levels, the requirement that the gra-
 197 dient Richardson number be smaller than 0.25 was also imposed [cf. *Grachev et al.*, 2013].
 198 As shown in *Stiperski and Calaf* [2018], existence of unstably stratified turbulence dur-
 199 ing nighttime points to non-local sources of turbulence and cannot be expected to fol-
 200 low scaling. In order to filter these counter gradient fluxes, theoretical incoming short-
 201 wave radiation was used to determine sunrise and sunset times together with the con-
 202 servative cross-over time of the daily cycle of sensible heat flux. This was particularly
 203 important for i-Box stations where a year of data was analyzed meaning that sunset and
 204 sunrise times varied significantly. No flux corrections were applied to the data, the same
 205 as in *Stiperski and Calaf* [2018].

206 **2.3 Anisotropy**

207 Traditionally, the Reynolds stresses ($\overline{u'_i u'_j}$) can be decomposed into an isotropic and
 208 anisotropic contribution, the latter being the one contributing the most to the transport
 209 of momentum [*Pope*, 2000]. The anisotropy contribution to scalar fluxes is also assumed
 210 to be important. The sum of the isotropic components of the Reynolds stress tensor is
 211 traditionally referred to as twice the turbulent kinetic energy ($2e = \overline{u'_i u'_i}$). In the above
 212 notation, a prime indicates a departure of a time-averaged quantity, and the overbar in-
 213 dicates the time-averaging operation. Additionally, the indices i, j vary between 1 to 3,
 214 in reference to the traditional Cartesian coordinate reference system with 1 indicating
 215 the streamwise, 2 the spanwise, and 3 the surface-normal directions, respectively.

216 The deviatoric anisotropy stress tensor defined as,

$$a_{ij} \equiv \overline{u'_i u'_j} - \frac{2}{3} e \delta_{ij}, \quad (1)$$

217 and in non-dimensional form (normalized by $2e$) as,

$$b_{ij} = \frac{\overline{u'_i u'_j}}{\overline{u'_l u'_l}} - \frac{1}{3} \delta_{ij}, \quad (2)$$

218 has long been studied in relationship to, for example, the pressure-strain correlation to
 219 develop models that capture the return-to-isotropy process once mean velocity gradients
 220 stop acting on the flow [*Rotta*, 1951; *Lumley and Newman*, 1977; *Lumley*, 1978; *Sarkar*
 221 *and Speziale*, 1990; *Choi and Lumley*, 2001]. Based on Lumley's work [*Lumley and New-*
 222 *man*, 1977; *Lumley*, 1978], it is possible to reduce the original three dimensional prob-
 223 lem characterized by six independent terms (normalized deviatoric anisotropy stress ten-
 224 sor) into a simpler problem with two degrees of freedom, based on the so-called anisotropy
 225 invariants, η and ξ [*Pope*, 2000] that are also functions of the eigenvalues (λ_i , $i = 1, 2, 3$)
 226 of the anisotropy stress tensor. The first invariant (η) is positive definite and provides
 227 a measure of the degree of anisotropy in the flow field (large values indicating intense
 228 anisotropy, and small values indicating near-isotropic behavior). The second invariant
 229 (ξ) can be positive or negative, indicating that the flow is dominated by one-component
 230 turbulence when positive, and by two-component turbulence when negative. These in-
 231 variants can be mathematically determined from the normalized deviatoric anisotropy
 232 stress tensor as [*Pope*, 2000]

$$6\eta^2 = b_{ij} b_{ji} \quad \text{and} \quad 6\xi^3 = b_{ij} b_{jk} b_{ki}. \quad (3)$$

236 As a result, it is possible to represent any realizable state of turbulence on a sin-
 237 gular two-dimensional non-linear map, the so-called Lumley Triangle (LT, *Lumley* [1978];
 238 *Pope* [2000]). Here, instead, we use a modification of the original LT, the Barycentric
 239 Lumley Triangle (BLT, *Banerjee et al.* [2007], see Figure 2 and Table 2), that overcomes
 240 the complexity associated with the non-linearity of the LT by equally weighing the dif-
 241 ferent limiting states of turbulence anisotropy. The corresponding coordinates (x_B , y_B)

233 **Table 2.** Summary of the special states of the Reynolds-stress tensor in terms of the invariants (η ,
 234 ξ), and the eigenvalues of the anisotropy stress tensor as described by the Lumley Triangle. The fourth
 235 column introduces the corresponding ellipsoid shape described by the eigenvectors [Pope, 2000].

Cases	Invariants	Eigenvalues	Shape ellipsoid
Isotropic	$\eta = \xi = 0$	$\lambda_1 = \lambda_2 = \lambda_3 = 0$	Sphere
Two-component axisymmetric	$\eta = \frac{1}{6}, \xi = -\frac{1}{6}$	$\lambda_1 = \lambda_2 = \frac{1}{6}$	Disk
One-component	$\eta = \xi = \frac{1}{3}$	$\lambda_1 = \frac{2}{3}, \lambda_2 = \lambda_3 = -\frac{1}{3}$	Line
Axisymmetric, one large eigenvalue	$\eta = \xi$	$-\frac{1}{3} \leq \lambda_1 = \lambda_2 \leq 0$	Prolate Spheroid
Axisymmetric, one small eigenvalue	$\eta = -\xi$	$0 \leq \lambda_1 = \lambda_2 \leq \frac{1}{6}$	Oblate Spheroid
Two-component	$\eta = (\frac{1}{27} + 2\xi^3)^{1/2}$	$\lambda_1 + \lambda_2 = \frac{1}{3}$	Ellipse

242 of this linearized 2D map are related to the eigenvalues as

$$x_B = C_{1c}x_{1c} + C_{2c}x_{2c} + C_{3c}x_{3c} = C_{1c} + C_{3c}\frac{1}{2}, \quad (4)$$

$$y_B = C_{1c}y_{1c} + C_{2c}y_{2c} + C_{3c}y_{3c} = C_{3c}\frac{\sqrt{3}}{2}, \quad (5)$$

243 with the corresponding weights (C_{ic}) written as $C_{1c} = \lambda_1 - \lambda_2$, $C_{2c} = 2(\lambda_2 - \lambda_3)$, and
 244 $C_{3c} = 3\lambda_3 + 1$, with $x_{1C} = (1, 0)$, $x_{2C} = (0, 0)$, and $x_{3C} = (1/2, \sqrt{3}/2)$ indicating the
 245 limiting states of turbulence anisotropy in the BLT. Both invariant maps are equivalent
 246 given the existing relationship between the anisotropy invariants (η and ξ) and the eigen-
 247 values of the normalized anisotropy tensor (λ_i , Spencer [1971]),

$$\eta^2 = \frac{1}{3}(\lambda_1^2 + \lambda_1\lambda_2 + \lambda_2^2) \quad (6)$$

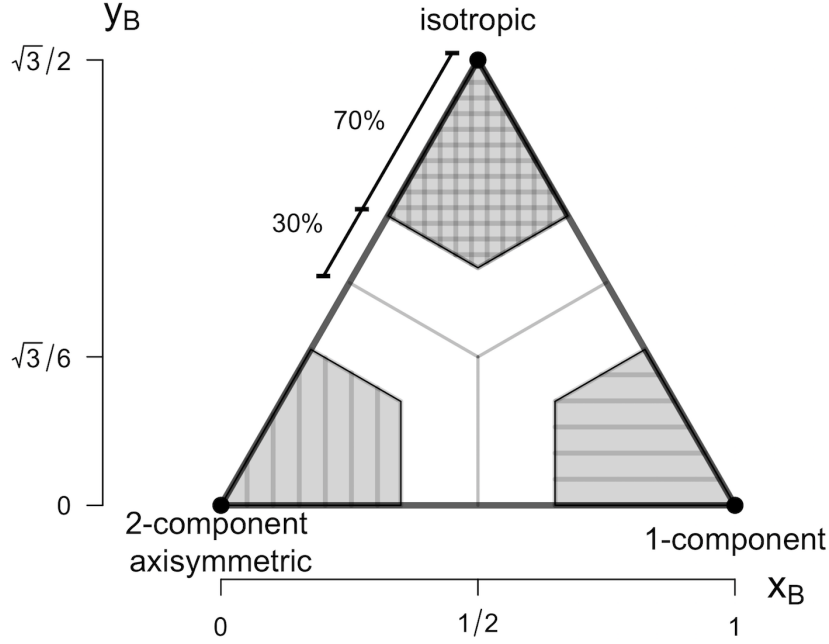
$$\xi^3 = -\frac{1}{2}\lambda_1\lambda_2(\lambda_1 + \lambda_2). \quad (7)$$

248 Finally, it is important to reiterate that the shape associated with the limiting states
 249 of anisotropy refers to the representation in eigenvalue space and not to the physical shape
 250 of turbulence itself [Simonsen and Krogstad, 2005]. More detail on the analysis of tur-
 251 bulence anisotropy can be found in [Stiperski and Calaf, 2018]

255 2.4 Scaling

256 Following Stiperski and Calaf [2018] we examine the influence of turbulence anisotropy
 257 on near-surface similarity within the local scaling framework [cf. Nieuwstadt, 1984a,b].
 258 Turbulent quantities are therefore scaled with the fluxes obtained at the corresponding
 259 measurement height z . The local Obukhov length Λ is defined as $\Lambda = \frac{-u_*^3\theta_v}{\kappa g w'\theta'}$, where
 260 θ_v is the mean virtual potential temperature, κ the von Karman constant, equal to 0.4,
 261 u_* the local friction velocity computed as $u_* = (\overline{u'w'^2} + \overline{v'w'^2})^{1/4}$ and $\overline{w'\theta'}$ is the local
 262 heat flux. The quantity $(z - d)/\Lambda$, where d is the displacement height, represents the
 263 local stability. We also define the local temperature scale as $\theta_* = -\frac{\overline{w'\theta'}}{u_*}$. The follow-
 264 ing functional forms of the surface-layer flux-variance similarity relationships are used
 265 for reference: for the standard deviations of velocity components (Φ_u, Φ_v, Φ_w), following
 266 Panofsky and Dutton [1984],

$$\Phi_w = \frac{\sigma_w}{u_*} = \begin{cases} 1.25(1 + 3\frac{z}{\Lambda})^{1/3} & \text{for } \frac{z}{\Lambda} > 0 \\ 1.25(1 - 3\frac{z}{\Lambda})^{1/3} & \text{for } \frac{z}{\Lambda} < 0 \end{cases} \quad (8)$$



252 **Figure 2.** Barycentric Lumley Triangle as a function of the anisotropy stress tensor eigenval-
 253 ues and represented through the linearized coordinates x_B and y_B . The shading indicates regions
 254 of the triangle that were selected as *pure* limiting states of anisotropy.

$$\Phi_{u,v} = \frac{\sigma_{u,v}}{u_*} = \begin{cases} 2.55(1 + 3\frac{z}{\Lambda})^{\frac{1}{3}} & \text{for } \frac{z}{\Lambda} > 0 \\ 2.55(1 - 3\frac{z}{\Lambda})^{\frac{1}{3}} & \text{for } \frac{z}{\Lambda} < 0 \end{cases} \quad (9)$$

267 for temperature standard deviation (Φ_θ), taking the reference curve from *Sfyri et al.* [2018],

$$\Phi_\theta = \frac{\sigma_\theta}{\theta_*} = \begin{cases} 2 + 6.7 \cdot 10^{-4} \frac{z}{\Lambda}^{-1.42} & \text{for } \frac{z}{\Lambda} > 0 \\ 1.67 - 0.016(\frac{z}{\Lambda})^1 & \text{for } -0.05 < \frac{z}{\Lambda} < 0 \\ 1.95(0.05 - \frac{z}{\Lambda})^{\frac{1}{3}} & \text{for } \frac{z}{\Lambda} < -0.05 \end{cases} \quad (10)$$

268 and for turbulence dissipation rate (Φ_ε), following *Thiermann* [1990],

$$\Phi_\varepsilon = \frac{kz\varepsilon}{u_*^3} = \begin{cases} (1 + 4\frac{z}{\Lambda} + 16(\frac{z}{\Lambda})^2)^{\frac{1}{2}} & \text{for } \frac{z}{\Lambda} > 0 \\ (1 - 3\frac{z}{\Lambda})^{-1} - \frac{z}{\Lambda} & \text{for } \frac{z}{\Lambda} < 0 \end{cases} \quad (11)$$

269 In the stable z-less limit *Sorbjan* [1987] suggested the following constant values of the
 270 flux-variance relationships

$$\Phi_w = 1.6, \quad \Phi_{u,v} = 3.1. \quad (12)$$

271 A number of quantitative measures are used to determine the amount of scatter
 272 between the datasets and the agreement with the reference scaling curves. Absolute de-
 273 viations $\Delta\Phi_y = |y - \Phi_y|$, where $y = u, v, w, \theta, \varepsilon$, are calculated as the absolute dis-
 274 tance between the scaled data y and the corresponding reference scaling curves (Eq. 8
 275 – 11). For stable conditions the z-less limit (Eq. 12) is used for the velocity components.
 276 For data separated according to anisotropy, the distance to the closest scaling line is em-
 277 ployed. This implies that for standard deviations of horizontal velocity components un-
 278 der isotropic conditions, the reference curve used in the calculation is Φ_w , and not $\Phi_{u,v}$
 279 [cf. *Stiperski and Calaf*, 2018]. The median of the absolute deviations (MAD) is used

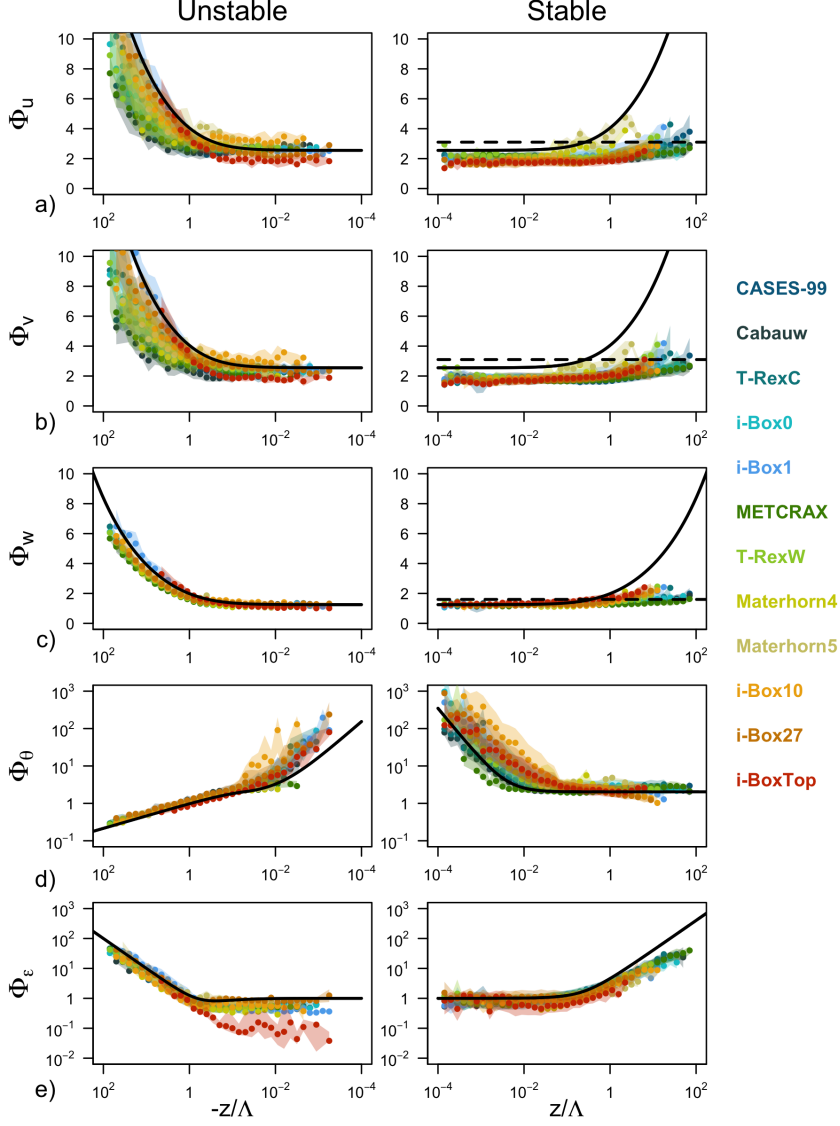
280 to quantify the mean disagreement of each dataset with the respective scaling as well as
 281 to quantify the complexity of the dataset. While the absolute value of MAD already pro-
 282 vides an indicator of the goodness of scaling, it is sensitive to the choice of the scaling
 283 curve and therefore might lead to large values if the choice is inadequate. Therefore, as
 284 a best indicator of the improvement in scaling, *i.e.* decreased variability in MAD between
 285 the different datasets, we use the inter-quartile range (*IQR*). It is calculated from the
 286 twelve MADs for each scaling variable and stability as the difference between the 75 and
 287 25 percentile. This measure provides information on the discrepancies between the dif-
 288 ferent datasets and the scaling curves and in that sense quantifies how ‘*location depen-*
 289 *dent*’ the scaling for different datasets is, and how much improvement is brought about
 290 by the new approach of *Stiperski and Calaf* [2018].

298 3 Results

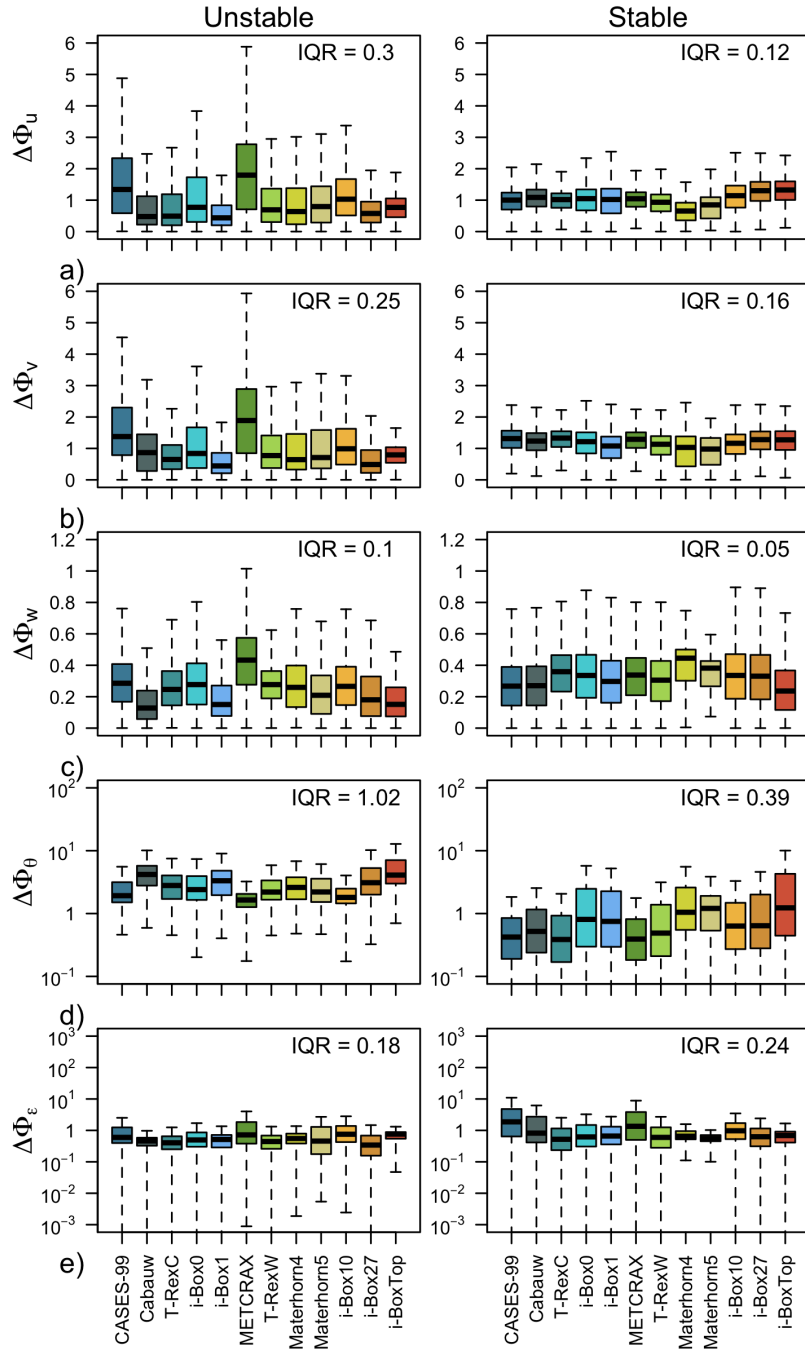
299 The scaled standard deviations of high-quality stationary data for each of the twelve
 300 datasets are shown in Figure 3 in comparison with the traditional similarity relations from
 301 horizontally homogeneous and flat terrain (Eq. 8 – 12). For visualization purposes the
 302 data from each dataset are binned and the median of each bin is displayed. The spread
 303 of the data is shown as the shading and corresponds to the inter-quartile range of each
 304 bin. The absolute deviations between the data and the reference scaling curves as well
 305 as inter-dataset spread are shown in Figure 4.

306 The results show large scatter both within each individual dataset (large shaded
 307 area in Figure 3) as well as between the different datasets (large *IQR* values in Figure
 308 4), confirming the ‘*location-dependent*’ nature of scaling in complex terrain. The large
 309 scatter within each dataset is particularly clear for horizontal velocity components $\Phi_{u,v}$
 310 in the very unstable region (cf. Figure 3a & b), to the point that the similarity relations
 311 can be deemed meaningless in that case. The same is true for the near-neutral regions
 312 for scaled temperature Φ_θ and less so for the scaled TKE dissipation rate Φ_ϵ . Notably,
 313 the vertical velocity variance exhibits good scaling behavior throughout, regardless of
 314 the dataset. This is particularly interesting given the large disparity of datasets used in
 315 this work, representative of very different terrain and flow complexities as well as ver-
 316 tical coordinates, which over flat terrain represent the vertical and in complex terrain
 317 the slope-normal direction. In the stable regime in general, the data scatter suggests a
 318 better collapse to a scaling curve (smaller *IQR* values in Figure 4 than for unstable data),
 319 particularly for weakly stable conditions of the velocity components $\Phi_{u,v,w}$. It is inter-
 320 esting to note, however, that the scaled standard deviation of streamwise velocity Φ_u seems
 321 to suggest an ordering according to the datasets in the near-neutral regime, with some
 322 datasets showing a higher neutral limit than others, but all exhibiting a value lower than
 323 the HHF relation. The deviations from the reference scaling curves Eq. 8 – 9 in the very
 324 stable regime are quite substantial, indicative of, though not confirming, z-less scaling.
 325 This general behavior is slightly different for Φ_θ , where large scatter, mirroring that of
 326 the very unstable region of horizontal velocities, is present under weak stability, while
 327 data seem to scale better in the strongly stable regime.

332 In a first approximation, one may expect the results in Figure 4 to show an increas-
 333 ing deviation from the traditional scaling relations with increasing ‘complexity’ of the
 334 underlying terrain where the data were measured (see the subjective ordering of the datasets
 335 in Table 1 and the associated colors). Therefore, it could be expected that the smallest
 336 discrepancies are found for the most ideal sites such as CASES-99 (CA), Cabauw (CB),
 337 T-RexC and i-Box0 stations, and the biggest for data measured in stations located in
 338 very inclined terrain, such as i-Box10 and i-Box27 or i-BoxTop. Figure 4, however, shows
 339 that this is not the case and there is little to no correlation between the deviation from
 340 traditional scaling and the a-priori ordering of the datasets that was based solely on the
 341 slope angle-induced complexity. In fact, it can be observed that the discrepancies in scal-
 342 ing are generally the largest for CASES-99 and METCRAX II (Figure 4 a-c), despite



291 **Figure 3.** Scaling relations of the standard deviation of a) streamwise velocity (Φ_u), b) spanwise ve-
 292 locity (Φ_v), c) surface-normal velocity (Φ_w), d) temperature (Φ_θ) and d) TKE dissipation rate (Φ_ε) as a
 293 function of the local stability z/Λ for unstable (left) and stable (right) stratification. Colors represent dif-
 294 ferent datasets described in Table 1. Points represent medians calculated over the bins of logarithmically-
 295 spaced z/Λ , while the shading corresponds to the inter-quartile range. The full black lines correspond to
 296 the traditional scaling relations (Eq. 8 – 11) and dashed lines to the z -less scaling for each variable (Eq.
 297 12).



328 **Figure 4.** Box plots of absolute deviations a) – e) $\Delta\Phi_y$ where $y = u, v, w, \theta$ and ε , respectively, of the
 329 scaled data from the corresponding scaling relations (Eq. 8 – 12): as a function of the dataset (color), for
 330 unstable (left column) and stable (right column) stratification. Note the different vertical axes for each
 331 variable. The value of the inter-quartile range (*IQR*) is listed in each panel.

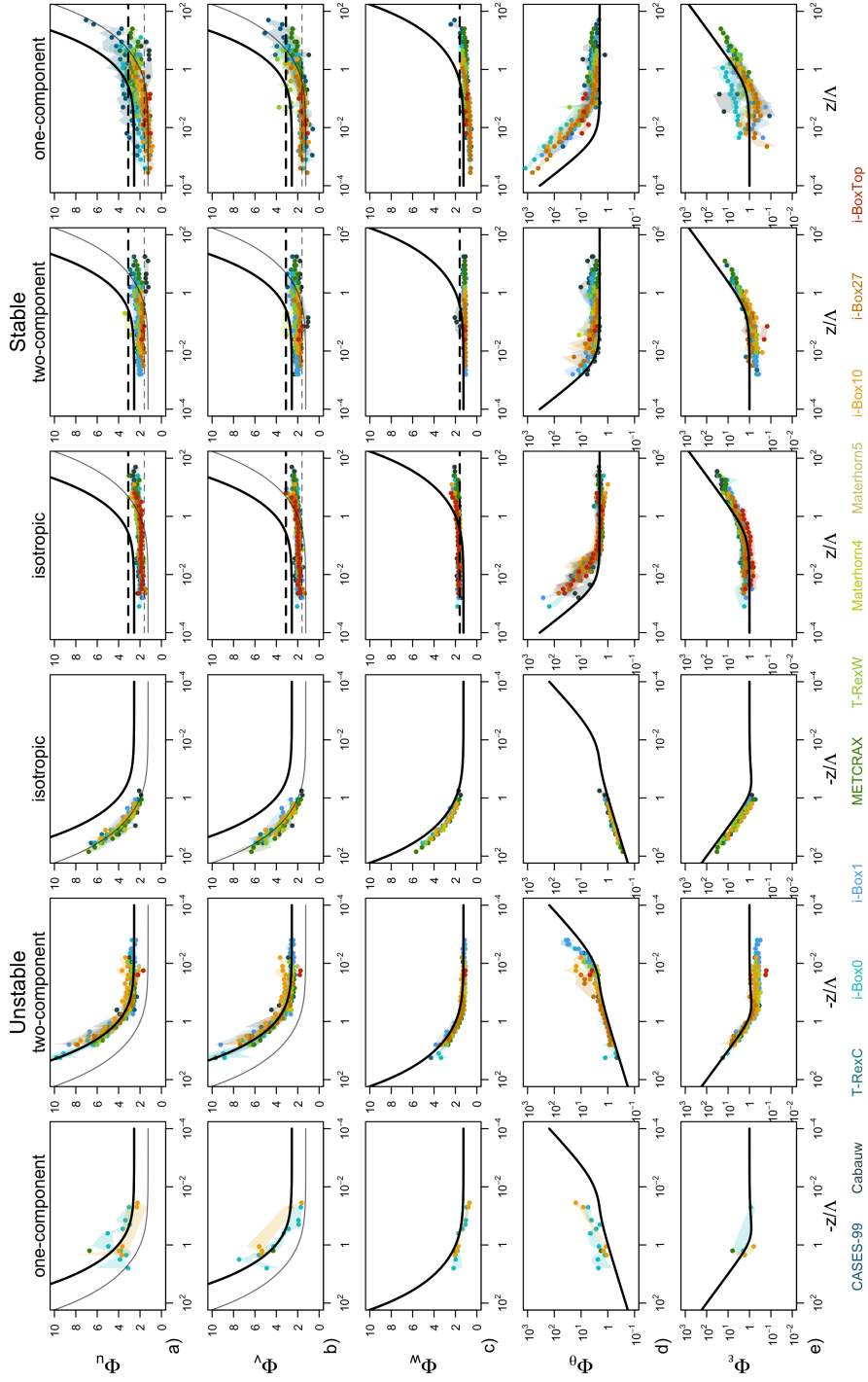


Figure 5. The same as Figure 3 but for data separated according to the pure states of anisotropy (isotropic, two-component axisymmetric and one component). The additional thin lines for the standard deviations of horizontal velocity components in a) and b) correspond to the scaling curve for Φ_w .

343 these being some of the most a-priori ideal locations (see Table 1). This mismatch with
 344 ordering of the datasets is present in all scaling variables, and particularly in unstable
 345 but also in stable stratification, suggesting that our simple classification of datasets based
 346 on slope angle is not corresponding to the true nature of their complexity.

347 Following the approach developed in *Stiperski and Calaf* [2018], next we separate
 348 the data according to the three limiting states of anisotropy: isotropic, two-component
 349 axisymmetric and one-component turbulence, before revisiting the scaling relations (Fig-
 350 ure 5). Figure 6 shows the MAD and *IQR* as objective measures of the improvement of
 351 the scaling. Mirroring the results for flat terrain (CASES-99 in *Stiperski and Calaf* [2018]),
 352 accounting for turbulence topology drastically improves scaling (*i.e.*, decreases MAD and
 353 *IQR*) for all datasets regardless of the complexity induced by terrain and local weather
 354 conditions. For all variables, the most consistent reduction in *IQR* and overall the best
 355 scaling behavior is apparent for isotropic turbulence both under unstable and stable strat-
 356 ification, and for unstable two-component axisymmetric turbulence (Figure 6). Compared
 357 to Figure 4, the largest improvement is obtained for the horizontal velocity components
 358 under unstable stratification with MAD and *IQR* reduced by up to 60%. As already found
 359 for CASES-99 by *Stiperski and Calaf* [2018], isotropic and two-component axisymmet-
 360 ric turbulence for horizontal velocity variances follow two distinctly different scaling lines.
 361 We come to the same conclusion as *Stiperski and Calaf* [2018] that this clustering of the
 362 data to two different scaling curves is the leading cause of the large scatter illustrated
 363 in Figure 3 a&b and Figure 4 a&b in the very unstable region. It is interesting to note
 364 that for all datasets, irrespective of complexity, isotropic turbulence occupies the same
 365 region of z/Λ as for flat terrain (*i.e.* $z/\Lambda < -1$). This is a clear sign of TKE produc-
 366 tion in isotropic turbulence being thermally dominated [*Stiperski and Calaf*, 2018] ir-
 367 respective of terrain complexity. On the other hand, in complex terrain, two-component
 368 axisymmetric turbulence is found also in very unstable conditions, contrary to the re-
 369 sults over flat terrain (CASES-99 in *Stiperski and Calaf* [2018]). The small amount of
 370 data points corresponding to unstable one-component turbulence does not allow us to
 371 reach definite conclusions about similarity of this type of turbulence. The results do seem
 372 to suggest a larger degree of scatter and therefore a lack of proper scaling.

373 In the stable regime, the scaled standard deviations of all velocity components fol-
 374 low the z-less scaling up to $z/\Lambda \approx 1$ whereupon the data start to deviate from their con-
 375 stant value. This is opposite to the general expectations for z-less scaling and might be
 376 an indication of self-correlation [*Klipp and Mahrt*, 2004]. The least scatter between the
 377 datasets (smallest *IQR*) is observed for isotropic turbulence. This is true even for the
 378 standard deviation of temperature, but only over a very limited range of stability. The
 379 near-neutrally stable region of Φ_θ shows large scatter, which is likely another indication
 380 of self-correlation as found by *Sfyri et al.* [2018]. In addition, the negative slope of the
 381 Φ_θ scaling only appears at larger stability for both isotropic and one-component turbu-
 382 lence than suggested by the HHF curve. This *shifted* linear decrease in the relation be-
 383 tween temperature variability and heat flux explains the large $\Delta\Phi_\theta$ (Figure 4d), *i.e.*, the
 384 deviation of the datasets from the scaling relations. The two-component axisymmetric
 385 and one component turbulence show progressively more scatter (larger *IQR*) compared
 386 to isotropic turbulence but also a reduction of the value of the scaled standard devia-
 387 tions of velocity components ($\Phi_{u,v,w}$) and TKE dissipation rate (Φ_ϵ), and an increase
 388 in the scaled standard deviation of temperature (Φ_θ). This suggests that, at least for sta-
 389 ble stratification, *i.e.* when mechanically produced turbulence is being damped by nega-
 390 tive buoyancy, anisotropic turbulence tends to have a larger temperature variance but
 391 smaller velocity variances in relation to the respective fluxes. One component turbulence
 392 is again the turbulence topology that exhibits most scatter, particularly for Φ_u and Φ_ϵ .
 393 It is particularly interesting to note that the station with the most complex conditions
 394 (iBoxTop) shows largest deviations from scaling for unstable stratification, but on the
 395 other hand does not exhibit systematic deviations for stable stratification but rather falls
 396 within those of the other datasets.

397 These results confirm our initial hypothesis that anisotropy is the key variable miss-
 398 ing from scaling relations. Indeed, anisotropy seems to provide a direction towards a uni-
 399 fying framework for turbulence in conditions where the assumptions of Monin-Obukhov
 400 Similarity Theory are generally violated, such as complex terrain or other sources of com-
 401 plex weather patterns that might affect the local flow.

402 Because separating the data according to anisotropy does significantly improve scal-
 403 ing, we first attempt to explain the large scatter between and within the original datasets
 404 observed in Figures 3 and 4 by focusing on the frequency of occurrence of a given pure
 405 state of anisotropy. This is done to examine whether local topographic dissimilarities be-
 406 tween the locations where the datasets were taken, cause different types of turbulence
 407 topologies to occur more or less frequently and thus converge towards different scaling
 408 curves leading to large scatter if examined together. Figure 7 shows the number of av-
 409 eraging periods for each pure turbulence state n (separated according to anisotropy and
 410 stratification) divided by the total number of averaging periods that are unstable or sta-
 411 ble n_{tot} . One can first note that turbulence states classified within the ‘*purely*’ isotropic,
 412 two- and one-component regimes (cf. Figure 2) only represent a small fraction of the over-
 413 all turbulence states. On average, the pure states of anisotropy jointly occur less than
 414 40% of the time for unstable stratification and less than 10% for stable stratification. This
 415 means that only a smaller part of the data originally shown in Figure 3 fulfills the more
 416 restrictive criterion for the pure states of anisotropy (cf. Figure 5). However, it also il-
 417 lustrates that the more pure states of anisotropy are those that have a stronger impact
 418 on similarity scaling, attracting the data towards different scaling curves as seen in Fig-
 419 ure 5. For example, both CASES-99 and METCRAX II have the largest proportion of
 420 isotropic turbulence, which accounts for the largest scatter in scaled horizontal veloc-
 421 ities in Figures 3 and 4 as mentioned above. *Stiperski and Calaf* [2018] already showed
 422 that unstable isotropic turbulence occurs mostly under conditions of free convection away
 423 from the surface, which coincides with the fact that all stations with prevailing isotropic
 424 turbulence are indeed located in areas that can be expected to frequently experience con-
 425 ditions supportive of free convection and generally have taller towers (flat terrain and
 426 more desert-like location, *e.g.* CASES-99, METCRAX II, MATERHORN, i-Box0). On
 427 the contrary, in complex terrain and close to the surface, isotropic turbulence hardly ever
 428 occurs (*e.g.*, i-Box27). The reason for this is the fact that in complex terrain thermally
 429 driven flows, characterized by strong horizontal and vertical wind shear [cf. *Goger et al.*,
 430 2018], develop in conditions that in flat terrain would support free convection (*i.e.*, weak
 431 shear). Given that different datasets were not only measured over different surfaces but
 432 also in different weather conditions we cannot isolate the influence of terrain on the fre-
 433 quency of pure anisotropic states by examining all the datasets together. Therefore, we
 434 focus next only on data from datasets obtained from multiple towers in close proxim-
 435 ity to each other and therefore experiencing similar weather conditions (*e.g.* T-Rex, MATER-
 436 HORN, i-Box). For example, T-Rex Central and West tower appear to have almost iden-
 437 tical percentages of pure states, thus suggesting that the slope angle does not play a ma-
 438 jor role on the anisotropy type there, at least not in unstable conditions. In stable con-
 439 ditions, the West tower on the slope has a marginally higher prevalence of isotropic data
 440 than the Central tower on the valley floor, suggestive of more developed turbulence there.
 441 Interesting are also the two MATERHORN towers both experiencing katabatic winds
 442 during nighttime [cf. *Grachev et al.*, 2016], however MT4 has a larger incidence of pure
 443 states than the MT5 tower, possibly due to its location in a less constrained topographic
 444 surrounding (open slope). For i-Box sites, the frequency of unstable two-component ax-
 445 isymmetric turbulence (stable isotropic turbulence) appears to decrease (increase) with
 446 increasing terrain complexity.

447 Still, even this classification approach fails to identify patterns that connect anisotropy
 448 and turbulence complexity. The available methodology consequently appears to be in-
 449 adequate to correctly describe the complexity of turbulence caused by both the terrain
 450 complexity (slope angle, heterogeneity, land use) and complexity of the flow conditions.

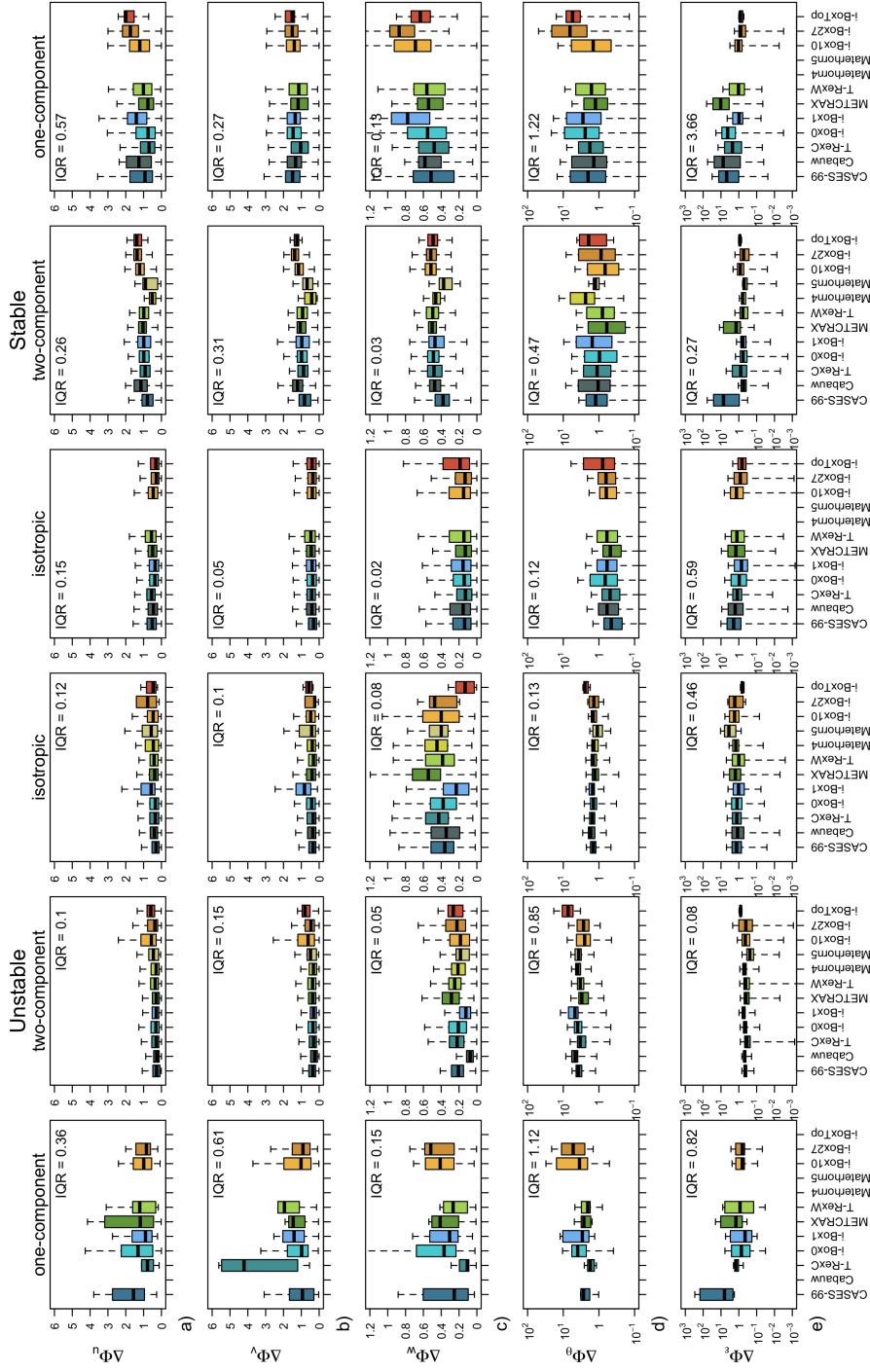
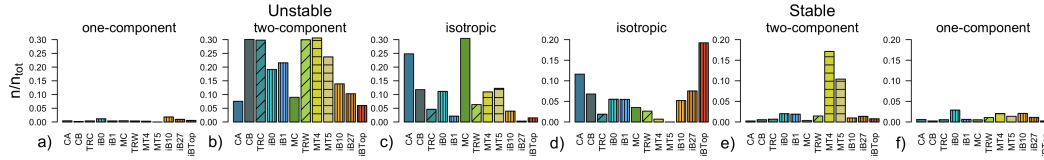


Figure 6. The same as Figure 4 but for turbulence separated according to the pure states of anisotropy. Note that here for isotropic turbulence Φ_w scaling relation is used as the reference.



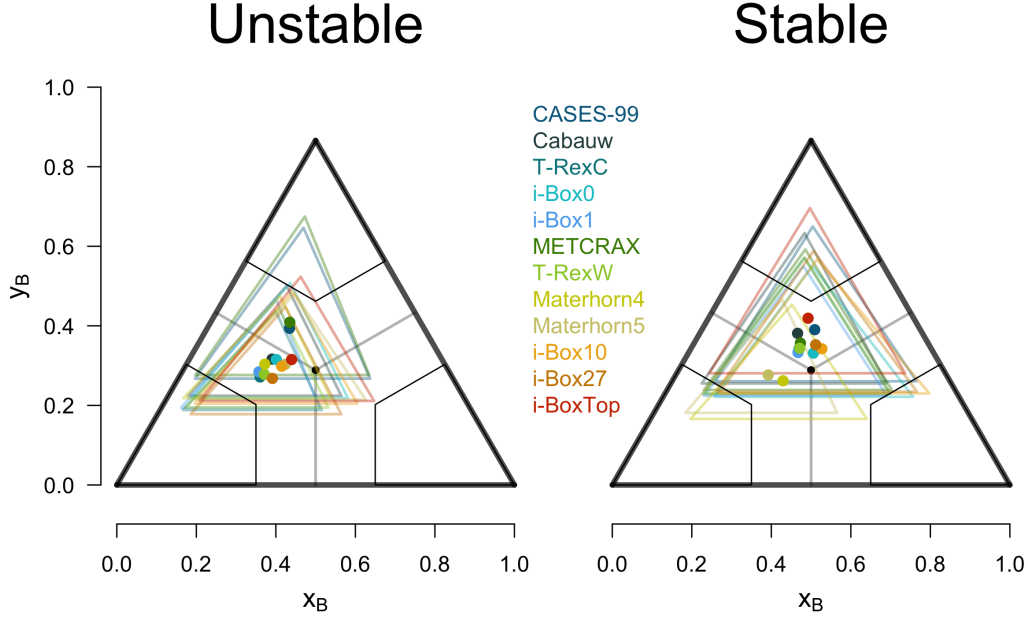
466 **Figure 7.** Frequency of occurrence (n/n_{tot}) of pure states of anisotropy (one-component, two-
 467 two-component axisymmetric and isotropic) for a)–c) unstable and d) – f) stable stratification. Here n is the
 468 number of averaging periods that are unstable/stable and at the same time belong to one of the pure
 469 anisotropy states, while n_{tot} is the total number of periods that are unstable/stable.

451 Therefore we propose instead to use the deviation from traditional similarity scaling rela-
 452 tions (MAD) as a measure of complexity of a given dataset. The encouraging results
 453 presented above make us confident that anisotropy is the dominant process causing the
 454 departure from scaling for unstable stratification and that including information on it
 455 would improve scaling relations. We therefore hypothesize that these deviations from scal-
 456 ing exist due to the fact that scaling relations are estimated in the physical, streamwise
 457 Cartesian coordinate system, whereas anisotropy is defined in the eigenvector reference
 458 frame. Similarly, *Klipp* [2018] suggested calculating the friction velocity in the eigenvec-
 459 tor space as a means of improving scaling relations. Here, we apply a different approach
 460 and instead use anisotropy as one of the explanatory variables that causes deviations from
 461 scaling curves. For stable stratification where anisotropy fails to improve scaling for two-
 462 and one-component turbulence, we identify other physical mechanisms that could be re-
 463 sponsible for the existence of complexity. We believe, that such an objective measure of
 464 complexity will not only allow better comparison between datasets but it can provide
 465 a pathway for developing new universal scaling relations.

470 4 Quantifying Complexity

475 We now take a step back and instead of focusing only on the pure states of anisotropy,
 476 we look at all the turbulence states (including mixed states) of anisotropy together. Fig-
 477 ure 8 shows where the centre of mass in the BLT resides for each dataset. The size of
 478 the colored triangle represents the spread of the data and is calculated as the 75th per-
 479 centile in x and y direction. The centres of mass show that, for unstable stratification,
 480 data are mostly centered between the isotropic and two-component axisymmetric states,
 481 whereas for stable conditions they are more evenly spread between the two- and one-component
 482 states but generally closer to the isotropic limit. The same as with frequency of occur-
 483 rence of pure states, the information on the centre of mass does not provide a conclu-
 484 sive information on the causes of turbulence complexity.

485 Complexity in the atmospheric boundary layer can be caused by a number of pro-
 486 cesses acting on a range of scales. While we use the departure from the scaling curve as
 487 a measure of complexity, the causes of this departure have to be identified manually from
 488 a number of possible processes known to be relevant in complex terrain [cf. *Serafin et al.*,
 489 2018]. These include (but are not limited to) the influence of terrain, where the easiest
 490 measure of terrain influence is the slope angle α . Although in the analysis so far, slope
 491 angle did not show a systematic influence on scaling, the inclination of terrain can still
 492 act indirectly and this influence is therefore examined. Heterogeneity, although a signif-
 493 icant source of complexity due to the formation of internal boundary layers as well as
 494 secondary circulations, is hard to quantify from experimental data and is therefore not
 495 examined here. Secondly, given the success of anisotropy in improving scaling in the re-
 496 sults of the previous section, we examine anisotropy itself as a dominant variable influ-
 497 encing complexity. We use the coordinates of the BLT as scalar measures of anisotropy
 498 that encompasses all types of anisotropy (cf. Figure 8). Here y_B represents the shortest



471 **Figure 8.** Barycentric Lumley Triangle showing the centre of mass for all the data points
 472 within the triangle for each dataset and stability. Different datasets are shown in color. Colored
 473 triangles represent the amount of spread of the data (calculated from the 75th percentile, and are
 474 calculated around the centre of mass.

499 distance to pure isotropy similarly to what was used in [Brugger *et al.*, 2018], while x_B
 500 shows where in between two-component axisymmetric and one-component state the tur-
 501 bulence is situated. Two mesoscale processes are ubiquitous in complex terrain: thermally-
 502 driven flows (up/down-valley, up/down-slope) and shallow water effects such as gravity
 503 waves. Thermally-driven flows are characterized by significant wind turning with height
 504 [Rotach *et al.*, 2008]. The impact of this directional shear can be measured through the
 505 angle between the streamwise $\overline{u'w'}$ and spanwise $\overline{v'w'}$ momentum flux components, de-
 506 fined as

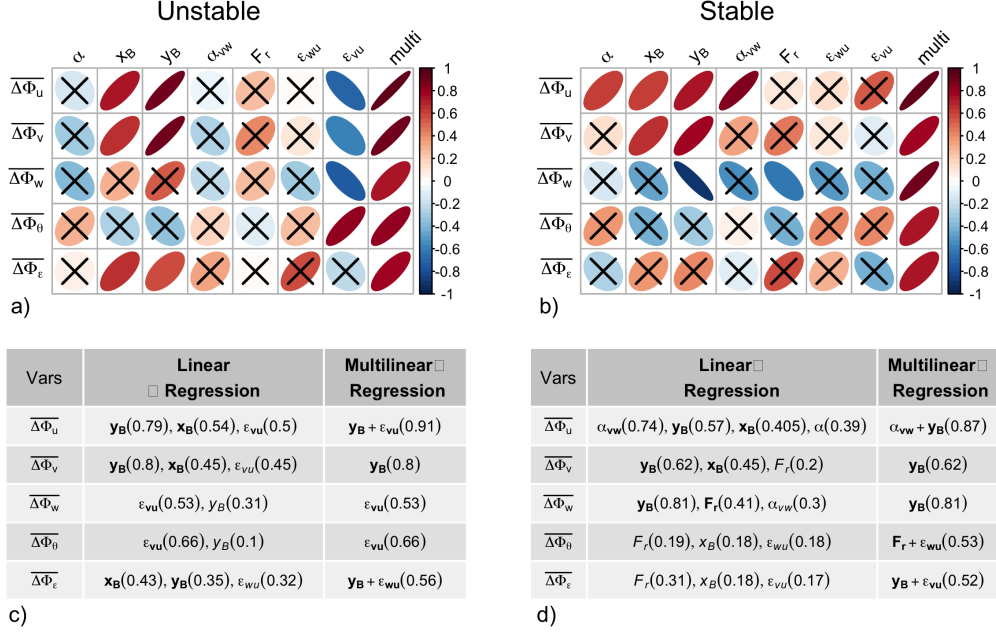
$$\alpha_{vw} = \tan^{-1}\left(\frac{\overline{v'w'}}{\overline{u'w'}}\right). \quad (13)$$

507 If there is no directional shear, $\overline{v'w'} = 0$, then α_{vw} will also be zero as all the turbu-
 508 lence exchange of momentum will occur along the streamwise direction (recall that the
 509 double rotation orientates the coordinate system into the direction of the mean wind speed).
 510 The effect of wind turning on turbulence is therefore indirect, since it does not depend
 511 on driving parameters at the level where the momentum flux is measured but at heights
 512 below and above. This measure is convenient since it provides information on wind turn-
 513 ing even if measurements are available only at one measurement level. Shallow water modes,
 514 such as gravity waves, may also affect turbulence [Sun *et al.*, 2015] and can be quanti-
 515 fied through the Froude number

$$F_r = \frac{U}{\sqrt{gH}}, \quad (14)$$

516 where H is the layer depth. Given that we have no way of determining the depth scale
 517 H from the available measurements, it has to be parameterized. For this purpose we use
 518 a modified boundary layer height following Zilitinkevich *et al.* [2012],

$$H = \frac{\overline{w'w'}}{\sqrt{|fw\theta g/\theta|}}, \quad (15)$$



527 **Figure 9.** a) - b) Correlation matrix between the observed deviations from scaling
 528 ($\overline{\Delta\Phi_y}, y = u, v, w, \theta, \varepsilon$) and the relevant variables representing physical processes for a) unsta-
 529 ble and b) stable stratification. The correlation coefficients are shown in color and shape so that
 530 perfectly circular shape means zero correlation and perfect line has correlation coefficient equal
 531 to 1. Crosses signify correlations that are not statistically significant at a 5 % level. c) - d) List
 532 of statistically significant ($p < 0.05$) variables and their respective R^2 values from the linear
 533 and multilinear regression with $\overline{\Delta\Phi_y}, y = u, v, w, \theta, \varepsilon$ for c) unstable and d) stable stratification.
 534 Variables that are statistically significant are shown in bold.

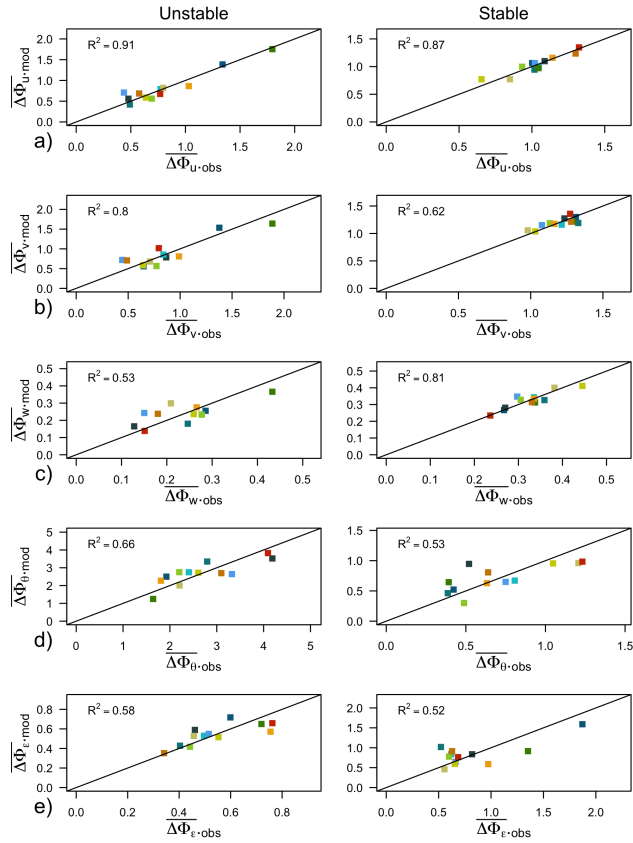
519 where f is the Coriolis parameter, and we use the vertical velocity variance instead of
 520 friction velocity, following *Monti et al.* [2002].

521 Finally, the influence of the smaller-scale anisotropy *i.e.* anisotropy in the inertial
 522 subrange [cf. *Katul et al.*, 1995; *Toschi et al.*, 2000; *Poggi et al.*, 2003], can be estimated
 523 through the ratio of turbulence dissipation rates

$$\varepsilon_{vu} = \varepsilon_v / \varepsilon_u, \varepsilon_{wu} = \varepsilon_w / \varepsilon_u. \quad (16)$$

524 Here ε_i is the dissipation rate as determined from the spectral density in the inertial sub-
 525 range of the velocity component i . *Babić and Rotach* [2018] have shown that over het-
 526 erogeneous surfaces these ratios, particularly ε_{wu} , can deviate strongly from one.

538 In order to identify which of these processes are relevant in complex terrain and
 539 therefore causing largest departures from scaling we first individually employ the linear
 540 regression approach to determine the correlation between the departure from scaling $\overline{\Delta\Phi_y}, y =$
 541 $u, v, w, \theta, \varepsilon$ and the corresponding predictor variables ($x_B, y_B, \alpha, \alpha_{vw}, F_r, \varepsilon_{vu}, \varepsilon_{wu}$). The
 542 correlation coefficients are shown in Figure 9 for unstable and stable stratification. Sec-
 543 ondly, a multilinear regression with the relevant variables was performed to estimate the
 544 joint influence of these processes on the departure from scaling. How many and which
 545 variables were chosen for the multilinear regression was determined in a step-wise man-
 546 ner. From the step-wise procedure we choose as final the combination of statistically sig-
 547 nificant variables ($p < 0.05$) with the largest R^2 and smallest Bayesian Information Cri-
 548 terion (*BIC*; *Wilks* [2011]). The variables in linear and multilinear regression are shown



535 **Figure 10.** Comparison of observed deviations from scaling ($\overline{\Delta\Phi_{y_{obs}}}$) and those modelled
 536 by multilinear regression ($\overline{\Delta\Phi_{y_{mod}}}$) using variables from Figure 9c & d (Multilinear regression).
 537 Here $y = u, v, w, \theta, \epsilon$.

549 in Figure 9 c&d, and the observed departures from scaling and the ones predicted by mul-
 550 tilinear regression are shown in Figure 10. The largest limitation of this approach is of
 551 course the assumption of a linear relationship between predictors and the explanatory
 552 variable.

553 The results of both linear and multilinear regression (Figure 9) show that y_B and
 554 therefore the shortest distance to isotropic state is truly one of the most important ex-
 555 planatory variables both in unstable and stable stratification, confirming the results of
 556 the previous section. Indeed, y_B can explain up to 80% of variability between the com-
 557 plex terrain scaling relations for certain variables and stability ranges. The correlation
 558 with y_B is positive indicating that the increase of complexity coincides with the depar-
 559 ture from isotropic conditions. In the unstable regime the other important process in-
 560 fluencing complexity is the small-scale turbulence anisotropy shown through ε_{vu} . Although
 561 the value of this ratio is within the 20% margin of one and therefore could be consid-
 562 ered almost constant (not shown), the individual values show a negative correlation with
 563 increasing complexity (apart from scaled temperature), indicating interestingly that the
 564 turbulence with a higher degree of horizontal small-scale isotropy is found in more com-
 565 plex conditions. These results are also contrary to *Babić and Rotach* [2018] where ε_{wu}
 566 diverges more from one. In the stable regime where anisotropy was successful in improv-
 567 ing scaling only in isotropic conditions, the mesoscale processes appear to be more im-
 568 portant than in the unstable regime. Therefore, wind turning with height (α_{vw}) and to
 569 a lesser degree the Froude number F_r appear to additionally explain an important part
 570 of the observed complexity.

571 The clear connection between $\Delta\Phi_{u,v}$ and y_B comes as no surprise given previous
 572 evidence that isotropic and two-component turbulence occupy different scaling curves,
 573 so that the distance to isotropy clearly delineates stations that have different percent-
 574 ages of these pure states and therefore cluster around them. On the other hand, in sta-
 575 ble stratification, it is the deviation of vertical velocity variance $\Delta\Phi_w$ that (anti)correlates
 576 best with y_B suggesting that unlike in unstable stratification, it is in the vertical veloc-
 577 ity component that anisotropy shows largest differences. This is intuitive given that as
 578 stratification increases, the vertical velocity variance decreases from isotropic towards
 579 one component with a progressively lower neutral limit, as observed in Figure 5. The im-
 580 portance of distinguishing between the very anisotropic states (two and one-component,
 581 *i.e.*, x_B) is also clearly identified as important for stable stratification, where one-component
 582 turbulence occurs more frequently. The existence of wind turning with height appears
 583 to have the largest influence on $\Delta\Phi_u$ in stable conditions, whereas scalar variances ap-
 584 pear to be most affected by gravity waves. The fact that the results are dependent on
 585 the ratio of the dissipation rates points to the scale-dependence of anisotropy and the
 586 persistence of anisotropy to very small scales. *Toschi et al.* [2000] have shown that this
 587 might be due to the effect of wind shear persisting across all scales.

588 Figure 9 shows that the multilinear combination of the above identified processes
 589 explains the majority of the variance for the standard deviation of velocity components,
 590 and to a lesser degree of the scalar variances (temperature and TKE dissipation rate)
 591 indicating the dissimilarity between the momentum and scalars *Brutsaert* [1982], but also
 592 pointing towards missing processes that have either not been identified by our limited
 593 list or are non-linear and therefore are not detected by the linear method.

594 5 Discussion and conclusions

595 The results of the previous sections have highlighted the importance of anisotropy
 596 in shaping the scaling relations, and have therefore shown that the approach of *Stiper-*
 597 *ski and Calaf* [2018] accounting for anisotropy, significantly improves scaling even over
 598 highly complex terrain. The large site-to-site variability in turbulence structure commonly
 599 found over complex terrain was then shown to be due to the differences in the frequency

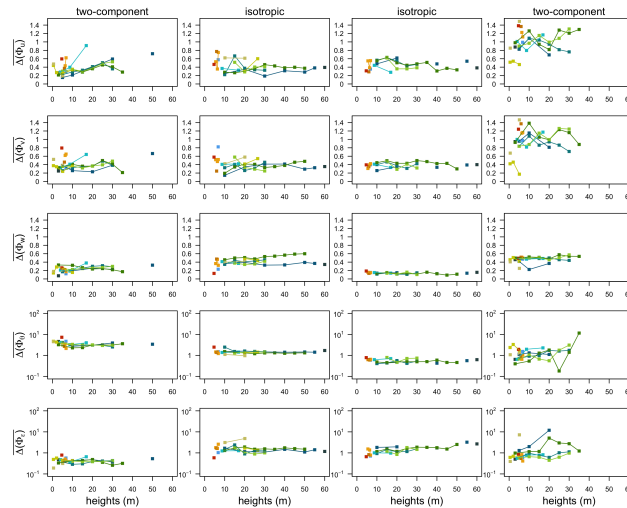
of occurrence of each anisotropy type, causing large scatter in the data, as different anisotropy states follow different scaling curves. For unstable stratification, anisotropy itself was found to be the dominant processes causing the failure of scaling among the various datasets. Whether the isotropic state or the two-component turbulence should actually be taken as the reference state in unstable stratification remains a question - especially since the atmospheric boundary layer turbulence is determined by the interplay between shear- and buoyancy-dominated turbulence (and the former is by definition anisotropic). Given the fact that two-component turbulence is more prevalent in unstable stratification and the data fit classic scaling relations better, suggests that the two-component limit is the reference state for unstable stratification. For stable stratification, isotropic turbulence is clearly the reference turbulence state, corresponding to weakly stable boundary layers with well-developed turbulence [cf. *Stiperski and Calaf, 2018*]. In stable stratification, however, we see that anisotropy itself cannot explain all the variability observed. It was therefore shown that physical mechanisms, such as wind directional shear, as well as effects of mean wind speed gradients persisting to the smallest scales and affecting turbulence in the inertial subrange, cause the complexity of turbulence. While these processes obviously occur also over flat and homogeneous terrain, they are more frequent and their effects more pronounced in complex terrain.

Another relevant issue associated with turbulence in complex terrain is the depth of the boundary layer [*Rotach and Zardi, 2007; De Wekker and Kossmann, 2015; Lehner and Rotach, 2018*], and consequently of the surface layer. Whereas we are employing local scaling (and not the Monin-Obukhov similarity scaling) and therefore do not require that the measurement levels are strictly within the surface layer, it is important to investigate the validity of this hypothesis. We therefore examine the median absolute deviations from scaling ($\overline{\Delta\Phi_y}$) as a function of measurement height for data separated according to anisotropy (Figure 11). Comparing the influence of height (stability) on scaling, shows that the height dependence within a given tower is on the same order as the site to site variability. Indeed, the deviations from scaling show almost no height dependence for isotropic turbulence, particularly for $\Phi_w, \Phi_\theta, \Phi_\varepsilon$. There is a larger but non-systematic variability for the horizontal velocity components under conditions of two-component axisymmetric turbulence, particularly for stable stratification, suggestive of intermittent conditions and layering associated with this type of very stable turbulence.

These results suggest that the physics represented by the newly introduced variables $y_B, \varepsilon_{vu}, \alpha_{vw}, F_r$ should be considered when working on the development of new scaling relations. Additionally, the present results suggest that the multilinear regression expressions such as found in this work could be used more effectively when determining complexity of a given dataset than traditional measures, such as slope angle. It is quite likely, however, that at least part of the remaining scatter (cf., Figure 9) will be associated with spatial (horizontal) heterogeneity, which is inherent in complex terrain but difficult to assess from single-tower observations. Before expressions for accounting for complexity in scaling relations themselves are used, this study would have to be extended to more than twelve datasets to improve its statistical significance. Of particular need in this respect would be horizontally distributed and long-term turbulence measurements from tall towers over very complex mountainous terrain. It is, however, already clear that this methodology provides a direction towards a unified theory of near-surface turbulence in terrains of all kinds of complexity. This will have particularly large implications for numerical modelling of weather and climate, where turbulence is parametrized by using scaling relations developed and hence only valid over flat and horizontally homogeneous terrain.

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649 **Figure 11.** Median absolute deviations from scaling $\overline{\Delta\Phi}_y, y = u, v, w, \theta, \epsilon$ as function of mea-
 650 surement height for unstable two-component axisymmetric and isotropic turbulence and stable
 651 isotropic and two-component axisymmetric turbulence.

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