

Razne formule

« Hidrodinamika »

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Razne jednačbe

1. Kronekerov simbol, jedinična matrica

$$\delta_{ij} = \begin{cases} 1 & \text{za } i = j \\ 0 & \text{za } i \neq j \end{cases} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

2. Antisimetrična matrica

$$e_{ijk} = \begin{cases} +1 & \text{za } i, j, k = 1, 2, 3 \quad \text{ciklička permutacija} \\ -1 & \text{za } i, j, k = 3, 2, 1 \quad \text{ciklička permutacija} \\ 0 & \text{za } i = j \text{ ili } j = k \text{ ili } k = i \end{cases}$$

Vrijedi

$$\vec{a} = \sum_i a_i \vec{e}_i, \quad a_i = a_x, a_y, a_z$$

$$\vec{b} = \sum_i b_i \vec{e}_i, \quad b_i = b_x, b_y, b_z$$

$$\vec{c} = \vec{a} \times \vec{b}, \quad c_i = \sum_{j,k} e_{ijk} a_j b_k$$

1. Gradijent

$$\vec{\nabla} n = \sum_i \vec{e}_i \frac{\partial n}{\partial x_i} = \vec{i} \frac{\partial n}{\partial x} + \vec{j} \frac{\partial n}{\partial y} + \vec{k} \frac{\partial n}{\partial z}$$

2. Divergencija

$$\vec{\nabla} \cdot \vec{v} = \sum_i \frac{\partial v_i}{\partial x_i} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

3. Rotacija

$$\vec{\nabla} \times \vec{v} = \sum_{i,j,k} e_{ijk} \vec{e}_i \frac{\partial v_j}{\partial x_k} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

4. Laplaceov operator

$$\Delta n = \frac{\partial^2 n}{\partial x^2} + \frac{\partial^2 n}{\partial y^2} + \frac{\partial^2 n}{\partial z^2}$$

Kombinacija derivacija skalarnih i vektorskih polja

1. $\vec{\nabla} \cdot \vec{\nabla} = \Delta$

2. $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) \equiv 0$

3. $\vec{\nabla} \times (\vec{\nabla} n) \equiv 0$

4. $\vec{\nabla}(n \vec{v}) = n (\vec{\nabla} \cdot \vec{v}) + (\vec{\nabla} n) \cdot \vec{v}$

5. $\vec{\nabla} \times (n \vec{v}) = n (\vec{\nabla} \times \vec{v}) + (\vec{\nabla} n) \times \vec{v}$

6. $\vec{\nabla} \times (\vec{\nabla} \times \vec{v}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) - (\vec{\nabla} \cdot \vec{\nabla})\vec{v} = \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) - \Delta \vec{v}$

7. $\vec{\nabla} \frac{\vec{v}^2}{2} = \vec{v} \times (\vec{\nabla} \times \vec{v}) + (\vec{v} \cdot \vec{\nabla})\vec{v}$

- ▶ Kartezijev

$$\vec{\nabla}n = \vec{i} \frac{\partial n}{\partial x} + \vec{j} \frac{\partial n}{\partial y} + \vec{k} \frac{\partial n}{\partial z}$$

- ▶ Cilindrični

$$\vec{\nabla}n = \vec{\rho}_0 \frac{\partial n}{\partial \rho} + \vec{\varphi}_0 \frac{1}{\rho} \frac{\partial n}{\partial \varphi} + \vec{k} \frac{\partial n}{\partial z}$$

- ▶ Sferni

$$\vec{\nabla}n = \vec{r}_0 \frac{\partial n}{\partial r} + \vec{\varphi}_0 \frac{1}{r \sin \vartheta} \frac{\partial n}{\partial \varphi} + \vec{\vartheta}_0 \frac{1}{r} \frac{\partial n}{\partial \vartheta}$$

Divergencija u raznim koordinatnim sustavima

- ▶ Kartezijev ($\vec{a} = a_x \vec{i} + a_y \vec{j} + a_z \vec{k}$)

$$\vec{\nabla} \cdot \vec{a} = \frac{\partial a_x}{\partial x} + \frac{\partial a_y}{\partial y} + \frac{\partial a_z}{\partial z}$$

- ▶ Cilindrični ($\vec{a} = a_\rho \vec{\rho}_0 + a_\varphi \vec{\varphi}_0 + a_z \vec{k}$)

$$\vec{\nabla} \cdot \vec{a} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho a_\rho) + \frac{1}{\rho} \frac{\partial a_\varphi}{\partial \varphi} + \frac{\partial a_z}{\partial z}$$

- ▶ Sferni ($\vec{a} = a_r \vec{r}_0 + a_\varphi \vec{\varphi}_0 + a_\vartheta \vec{\vartheta}_0$)

$$\vec{\nabla} \cdot \vec{a} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 a_r) + \frac{1}{r \sin \vartheta} \frac{\partial a_\varphi}{\partial \varphi} + \frac{1}{r \sin \vartheta} \frac{\partial}{\partial \vartheta} (\sin \vartheta a_\vartheta)$$

Rotacija u raznim koordinatnim sustavima

- ▶ Kartezijev ($\vec{a} = a_x \vec{i} + a_y \vec{j} + a_z \vec{k}$)

$$\vec{\nabla} \times \vec{a} = \vec{i} (\partial_y a_z - \partial_z a_y) + \vec{j} (\partial_z a_x - \partial_x a_z) + \vec{k} (\partial_x a_y - \partial_y a_x)$$

- ▶ Cilindrični ($\vec{a} = a_\rho \vec{\rho}_0 + a_\varphi \vec{\varphi}_0 + a_z \vec{k}$)

$$\vec{\nabla} \times \vec{a} = \frac{1}{\rho} \begin{vmatrix} \vec{\rho}_0 & \rho \vec{\varphi}_0 & \vec{k} \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \varphi} & \frac{\partial}{\partial z} \\ a_\rho & \rho a_\varphi & a_z \end{vmatrix}$$

- ▶ Sferni ($\vec{a} = a_r \vec{r}_0 + a_\varphi \vec{\varphi}_0 + a_\vartheta \vec{\vartheta}_0$)

$$\vec{\nabla} \times \vec{a} = \frac{1}{r^2 \sin \vartheta} \begin{vmatrix} \vec{r}_0 & r \vec{\vartheta}_0 & r \sin \vartheta \vec{\varphi}_0 \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \vartheta} & \frac{\partial}{\partial \varphi} \\ a_r & r a_\vartheta & r \sin \vartheta a_\varphi \end{vmatrix}$$

Laplacian u raznim koordinatnim sustavima

- ▶ Kartezijev

$$\Delta n = \frac{\partial^2 n}{\partial x^2} + \frac{\partial^2 n}{\partial y^2} + \frac{\partial^2 n}{\partial z^2}$$

- ▶ Cilindrični

$$\Delta n = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial n}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 n}{\partial \varphi^2} + \frac{\partial^2 n}{\partial z^2}$$

- ▶ Sferni

$$\Delta n = \frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial n}{\partial r} \right) + \frac{1}{r^2 \sin^2 \vartheta} \frac{\partial^2 n}{\partial \varphi^2} + \frac{1}{r^2 \sin \vartheta} \frac{\partial}{\partial \vartheta} \left(\sin \vartheta \frac{\partial n}{\partial \vartheta} \right)$$

- ▶ Eulerova jednadžba

$$\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v}(\vec{r}, t) = -\frac{1}{\rho} \vec{\nabla} p(\vec{r}, t) + \vec{g}$$

- ▶ Navier-Stokesova jednadžba

$$\rho \frac{D\vec{v}}{Dt} = \vec{f} - \vec{\nabla} p + \eta \Delta \vec{v} + \left(\zeta + \frac{\eta}{3}\right) \vec{\nabla}(\vec{\nabla} \cdot \vec{v})$$

- ▶ Jednadžba kontinuiteta

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{v}) = 0$$

- ▶ Bernoullijeva jednadžba

$$\frac{v^2}{2} + \frac{p}{\rho} + g z = \textit{konst.}$$